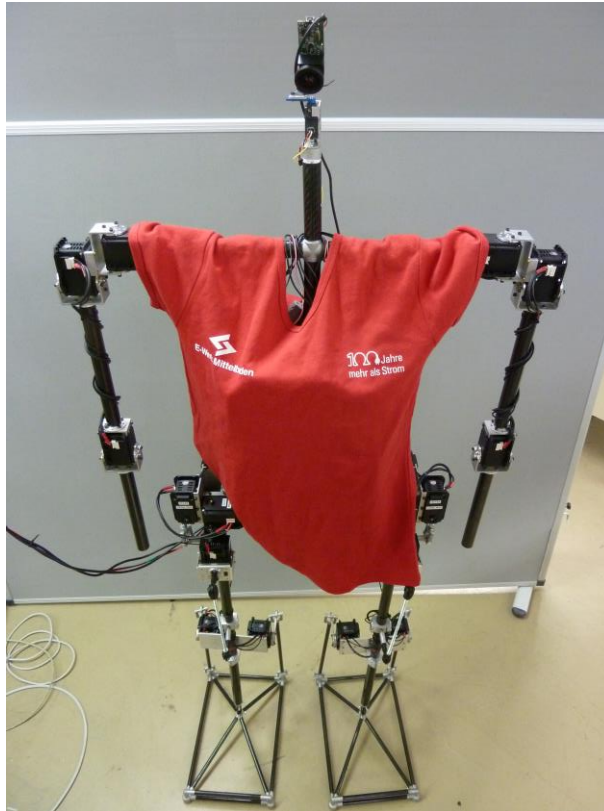


Sweaty



Robot Name:	Sweaty
Height of the robot:	140.5 cm
Weight of the robot:	10.1 kg
Walking speed:	0.2 m/s
Number of degrees of freedom:	19
Type of motors:	Robotis Dynamixel MX-106R, MX-64, Volz
Type of sensors used:	Logitech C905, Modified lens: 1,5" / focal distance 1,55 mm, Filter view 185° (partially covered, finally 180°)
Computing units:	Odroid XU, 4 x STM32F4
Height shoulder:	117 cm
Width shoulder:	54 cm
Height hip:	75 cm
Height torso:	38 cm
Length arm:	50 cm
Number and Typ of Buses	1x USB CDC, 2x RS485 2 MHz
Battery:	LiPo 4S1P 4 Ah 60C