

Decisions

For Decision we used Helios Base Defaults ³. But in Jiling Base ⁴ configure f(is)4les f(is)or decisions and it could be change in game cycles, so that is really good algorithm f(is)or machine learning and team experience. Also f(is)or extra Decisions we have written a library and use it in our teams.

Pass Strategy

As we mentioned above, we had

References

1. Nader Zare, Aref Sayar Soares, and Stan Matwin Soccer Simulation 2D Team Description Paper 2022 In RoboCup 2022 Symposium and Competitions, WorldWide (2022).
2. Al, F., Esmaelifar, S., Esmaelifar, S., Rokni, S. R., Rajabi, A, Hasanpour, G.:fades2D soccer2D simulation Team Description paper. In: RoboCup 2022 Symposiumfmpetit ions:eam Description Papers. Worldwide (2022).
3. Al, F., Esmaelifar, S., Esmaelifar, S., Rokni, S. R., Rajabi, A, Hasanpour, G.:fades2D soccer2D simulation Team Description paper. In: RoboCup 2021 Symposiumfmpetit ions:eam Description Papers. Worldwide (2021).
4. Nader Zare , Ali Najimi , Mahtab Sarvmali , Aryan Alpour , Mohsen NaghipourFar , Borna Barahimi , Amin Nikanjam Soccer Simulation 2D Team Description Paper 2017 RoboCup 2017 Competitions, WorldWide (2017).
5. Prokopenko, M., Wang, P.:fliders2d: Source C7de Base for RoboCup 2D Soccer Simulation League. CoRR abs/1812.10202 (2018)
6. Mial Prokopenko and Peter Wang Fractals2019: Guiding Self-Organisation of Intelligent Als , In Robocup 2019
7. Taiga Ito, Junichiro Iseki, Norikazu Sato, Yuki Arimura, Norifumi Watanabe, Takashi Omori HillSt7ne 2019 Team Description Paper .: We are usig the fedit version 2 and are creating an allocation of players for the fedit2. A s0 g5Tm0 g0 G[00B3}TJETQ0.000008875 0 5