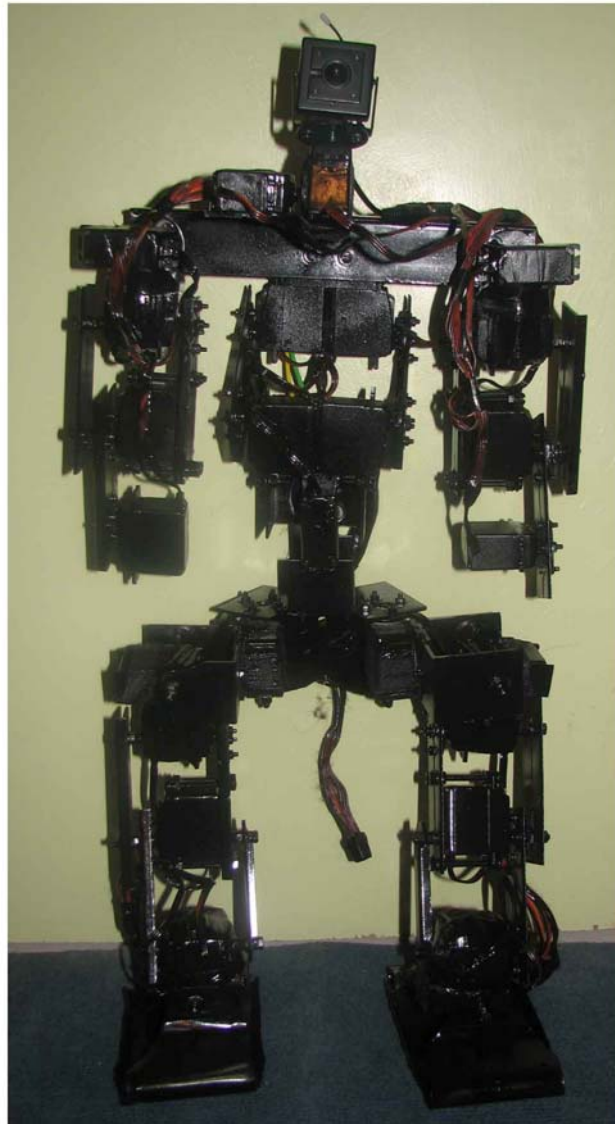


Robot Specification

Name : Robo Noble

Robot picture :



Number of degrees of freedom : 120 degrees

Type of motors : Servomotor

Computing Unit : Laptop

Camera :

CMOS Total Pixels	Pixels	628* 582(PAL)
View Angle	Degree	62
Minimum Illumination	Lux	1. 5 Lux/F 1. 5

Sensors : Camera & gyroscope & contact sensor
Walking speed :30 cm/s

Other specs:

Hand Length: 9.25 in

Distance Between Hands(closed): 11 in

Distance Between Hands(open): 26 in

Arm length: 4.5 in

Forearm Length: 2 in

Wrist Length: 2.75 in

Head and Neck Length: 3 in

Loin Length: 10 in

Foot Length: 10.78 in

Ankle Length: 3 in

Crus Length: 2.75 in

thigh Length: 5.12 in

Distance Between foot: 10 in

Sole Length: 5.12 in

Tall: 23 in

Weight: 4900 g