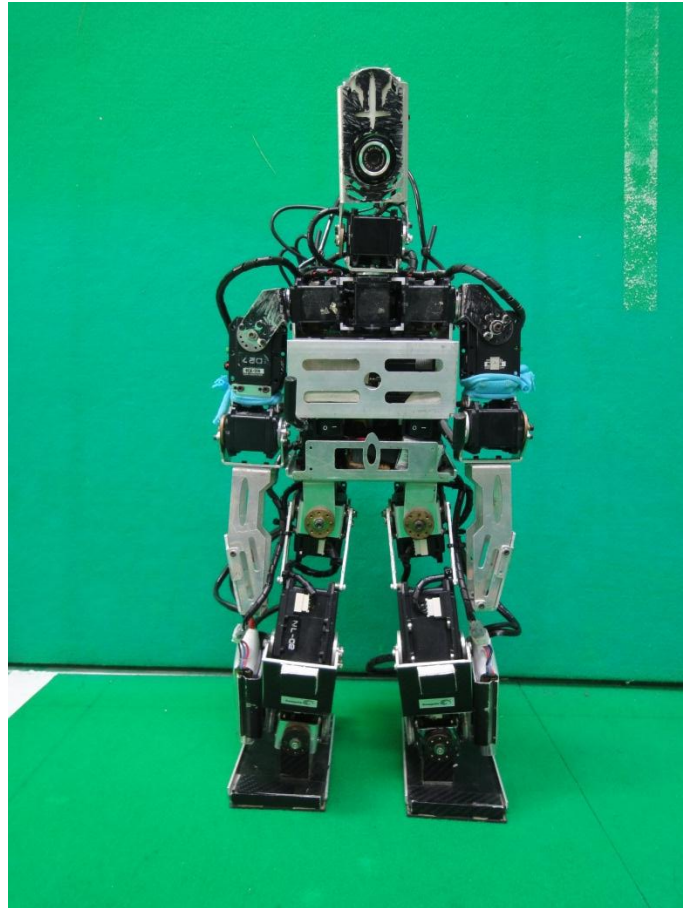
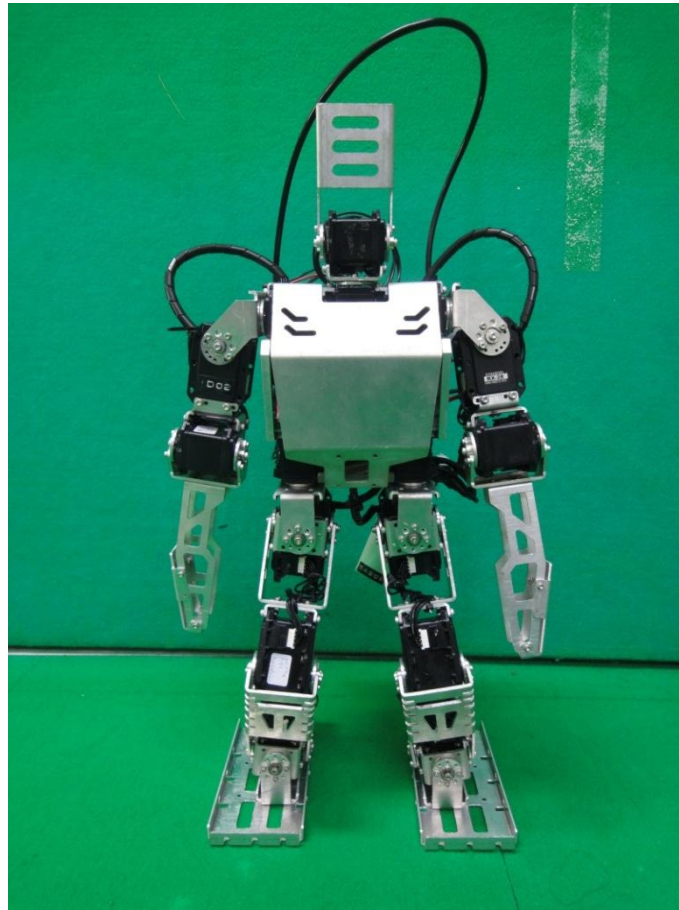


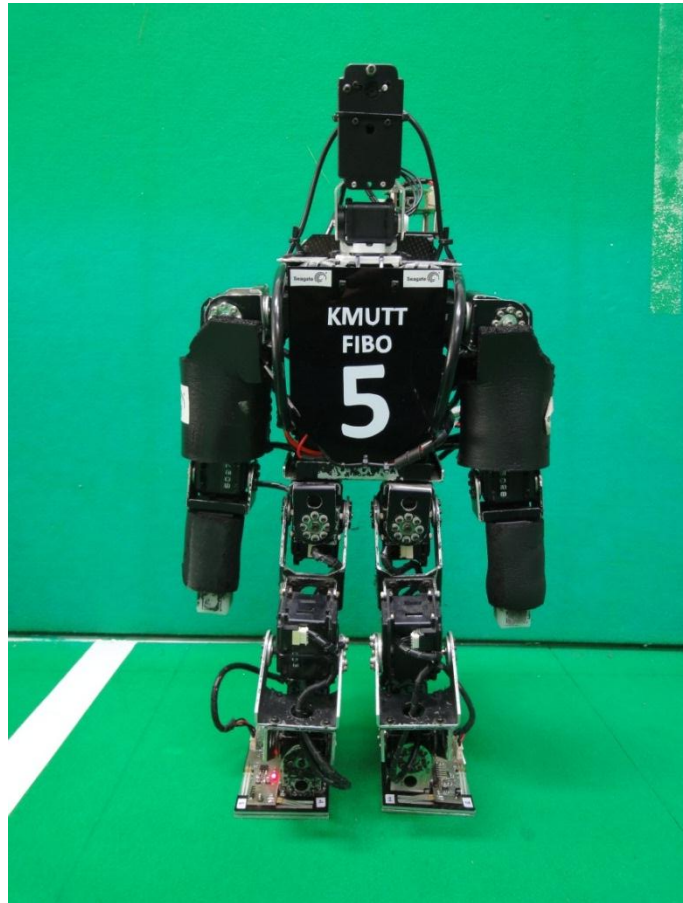
Robot Specification
Team Hanuman KMUTT



Name	Hanuman (Striker)
Height	50 cm
Weight	3.6 kg
Walking speed	~20 cm/sec
Sensors	2-axis gyro 2-axis accelerometer
Degree of freedom	20 DOF
Motors	18 Robotis RX-28 2 Robotis RX-64
Camera	Logitech Quickcam Pro
Computing Unit	PICO-ITX PC 1.6 GHz ARM7 TDMI-S 60MHz



Name	Tripetch , Muchanu (Striker)
Height	47 cm
Weight	3.1 kg
Walking speed	~20 cm/sec
Sensors	IMU 9 DOF
Degree of freedom	20 DOF
Motors	20 Robotis RX-28
Camera	Logitech Quickcam Pro
Computing Unit	PICO-ITX PC 1.6 GHz ARM7 TDMI-S 60MHz



Name	KM2 (Goalie)
Height	52 cm
Weight	3.6 kg
Walking speed	~20 cm/sec
Sensors	2-axis gyro 2-axis accelerometer
Degree of freedom	20 DOF
Motors	18 Robotis RX-28 2 Robotis RX-64
Camera	Havimo
Computing Unit	ARM7 TDMI-S 60MHz ATMEGA128 16MHz



Name	Palee (Goalie)
Height	57 cm
Weight	2.7 kg
Walking speed	~20 cm/sec
Sensors	IMU 9 DOF
Degree of freedom	20 DOF
Motors	20 Robotis RX-28
Camera	Havimo
Computing Unit	ARM7 TDMI-S 60MHz ATMEGA128 16MHz