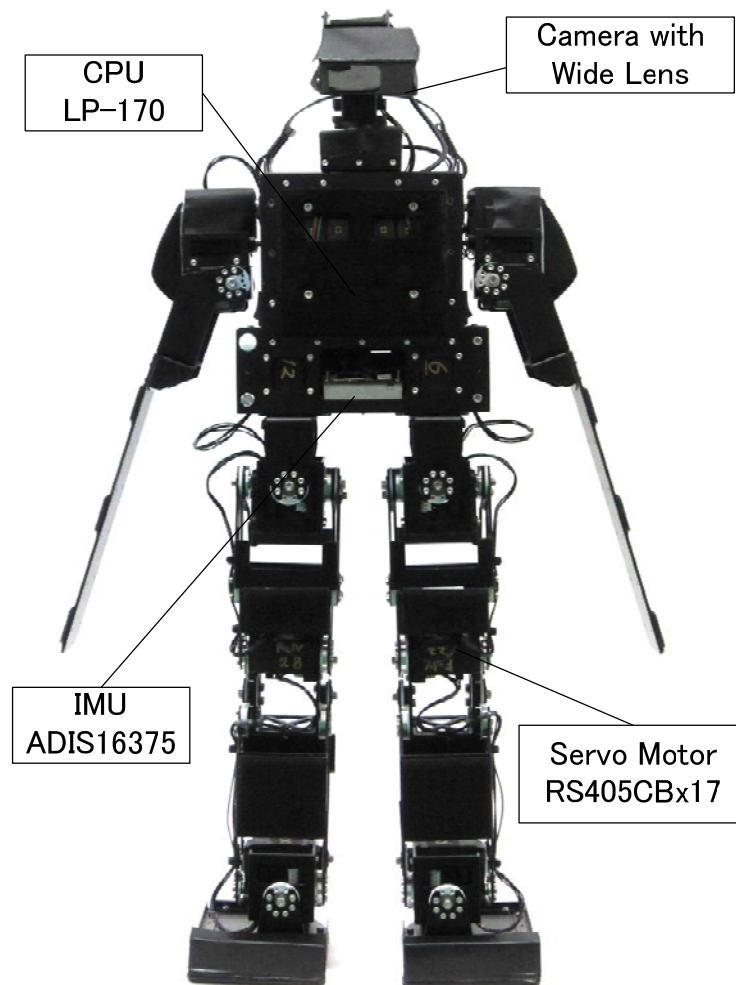


# CIT Brains (Kid Size League)

Yasuo Hayashibara, Hideaki Minakata, Kiyoshi Irie, Taiki Fukuda, Victor Tee Sin Loong, Daiki Maekawa, Yusuke Ito, Takamasa Akiyama, Taiitiro Mashiko, Kohei Izumi, Yohei Yamano, Masayuki Ando, Yu Kato, Ryu Yamamoto, Takanari Kida, Shinya Takemura, Yuhdai Suzuki, Nung Duk Yun, Shigechika Miki, Yoshitaka Nishizaki, Kenji Kanemasu, Hajime Sakamoto

yasuo.hayashibara@it-chiba.ac.jp



Robot name: Dynamo Accelite  
Height of the robot: 600mm  
Wight of the robot: 3.5kg  
Walking Speed: 0.4m/s  
Number of degrees of freedom: 17  
Type of motors: Futaba RS405CB  
Type of sensors used: USB Camera (Shikino High-Tech KBCR-M05VU)  
Analog Devices IMU ADIS16375  
Computing Unit: COMMELL LP-170 (Intel Atom D525)  
Other Specs: Wireless LAN (IEEE802.11a/b/g)