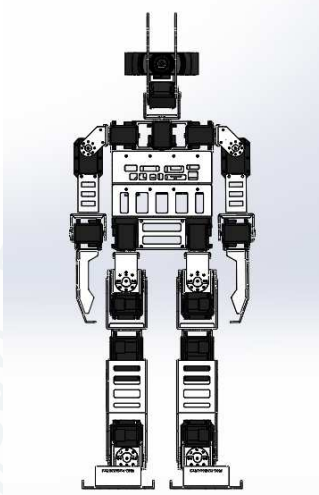



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Robot Specification

Image	 <p style="text-align: center;">X 3</p>
Robot name	FALCONBOT ONE
Height	60 cm.
Weight	3.9 kg
Walking speed cm / s	32 cm/s
Degrees Of Freedom and kind of Servomotors	DOF: 22, Dynamixel Mx28T, Dynamixel 64T Lents Dynamixel Mx64T X 10, Dynamixel Mx28T X 2 Arms Dynamixel Mx-28T X 8 Head Dynamixel MX-28T X 2
Sensors	Camera: Logitech C920 Gyroscope and Acelerometer include in Robotis CM730 Magnetometer: Sparkfun HMC6352.
Computacional Units	Main: FitPc 2i, intel atom 2.0 ghz, 2 gb RAM Subcontroller Robotis CM730.
Another specification	

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Image	 <p>X1</p>
Robot name	DARwIn OP
Height	45.5cm.
Weight	2.9 kg
Walking speed cm / s	30 cm/s
Degrees Of Freedom and kind of Servomotors	DOF: 20, Dynamixel Mx28T, legs Dynamixel Mx28T X 10 Arms Dynamixel Mx-28T X 8 Head Dynamixel MX-28T X 2
Sensors	Camera: Logitech C920 Gyroscope and Acelerometer include in Robotis CM730
Computacional Units	Main: FitPc 2i, intel atom 1.6 ghz, 1.0 gb RAM Subcontroller Robotis CM730.
Another specification	