

MRL Humanoid KidSize Robots Specification 2015

Physical measurements of redesigned DARwIn-OP robot.



Height:	45.5 cm
Weight:	2.8 Kg
Walking Speed:	24 cm/s
Degrees of freedom:	20 in total
Servo motors:	20 MX-28
Sensors:	Accelerometer gyroscope compass
Embedded PC board:	Fit-PC2i

Physical measurements of the Rabo robot.



Height:	58 cm
Weight:	5.2 Kg
Walking Speed:	36 cm/s
Degrees of freedom:	20 in total
Servo motors:	20 MX-64
Sensors:	Accelerometer gyroscope compass
Embedded PC board:	Fit-PC2i