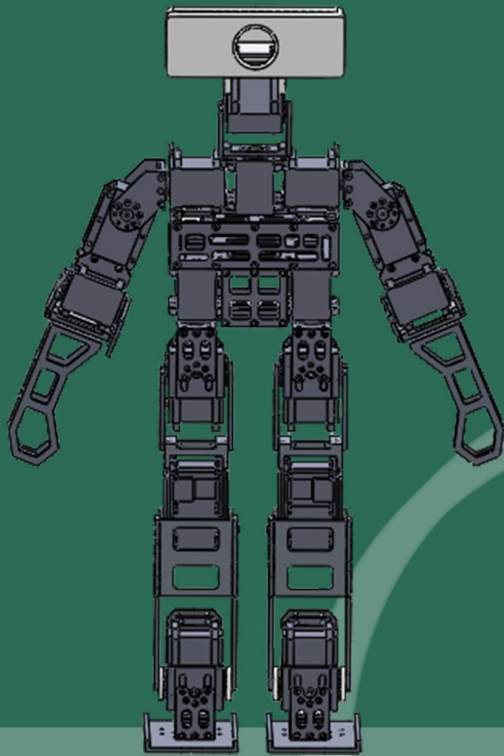


KUbot 3

Specification



Robot Name KUbot3

Height 479mm **Weight** 3kg

Number of DOF 20 in total

6DOF Leg X2

3DOF Arm X2

2DOF Head X1

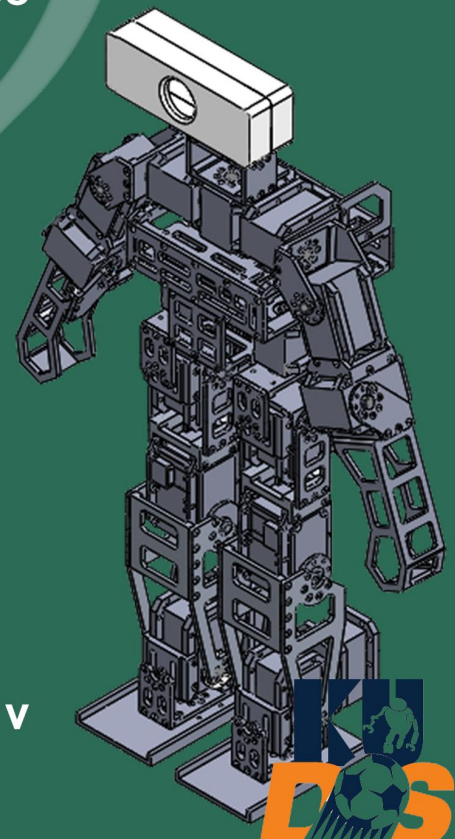
Actuator Dynamixel MX-28
Dynamixel MX-64

Control Unit Main controller : SBC-fitPC2i
Sub controller : CM-730

Type Of Camera Logitech C920

Type Of Senser Gyroscop
: 3-AXIS LYPR 540AH
Accelerometer
: 3-AXIS ADXL335
Magnetometer
: 3-AXIS AKM 8975

Other Spec Power : LiPo Battery 11.1v
Sound : Speaker, MIC
Display : Body LED



KUboteen1

Specification



Robot Name KUboteen1

Height 850mm **Weight** 6.7kg

Number of DOF 20 in total

6DOF Leg X2

3DOF Arm X2

2DOF Head X1

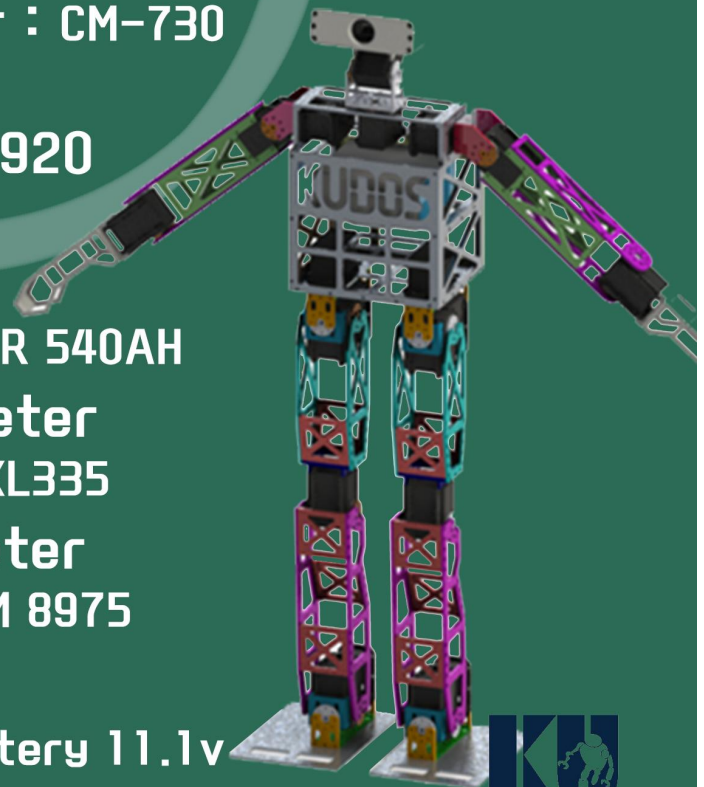
Actuator Dynamixel MX-64
Dynamixel MX-106

Control Unit Main controller : Intel NUC D34010WYK
Sub controller : CM-730

Type Of Camera Logitech C920

Type Of Senser Gyroscop
: 3-AXIS LYPR 540AH
Accelerometer
: 3-AXIS ADXL335
Magnetometer
: 3-AXIS AKM 8975

Other Spec Power : LiPo Battery 11.1v
Sound : Speaker, MIC
Display : Body LED



KUboteen2

Specification



Robot Name KUboteen1

Height 850mm **Weight** 7.6kg

Number of DOF 22 in total

7DOF Leg X2

3DOF Arm X2

2DOF Head X1

Actuator Dynamixel MX-64
Dynamixel MX-106

Control Unit Main controller : Intel NUC D34010WYK
Sub controller : CM-730

Type Of Camera Logitech C920

Type Of Senser Gyroscop
: 3-AXIS LYPR 540AH
Accelerometer
: 3-AXIS ADXL335
Magnetometer
: 3-AXIS AKM 8975

Other Spec Power : LiPo Battery 11.1v
Sound : Speaker, MIC
Display : Body LED

