

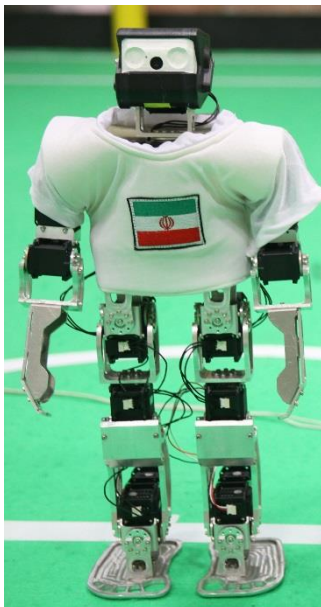
MRL Humanoid Kidsize Robots Specification 2016

Physical Measurements Of Redesigned Darwin-OP Robot.



Height:	45.5 cm
Weight:	2.8 kg
Walking Speed:	24 cm/s
Degrees Of Freedom:	20 In Total
Servo Motors:	20 MX-28
Sensors:	Accelerometer Gyroscope Compass Logitech C920 Camera
Embedded PC Board:	Fit-PC2i

Physical Measurements Of The Rabo-1 Robot.



Height:	58 cm
Weight:	5.2 kg
Walking Speed:	36 cm/s
Degrees Of Freedom:	20 In Total
Servo Motors:	20 MX-64
Sensors:	Accelerometer Gyroscope Compass Logitech C920 Camera
Embedded PC Board:	Fit-PC2i

Physical Measurements Of Rabo-2 Robot.



Height:	60 cm
Weight:	4.8 kg
Walking Speed:	36 cm/s
Degrees Of Freedom:	20 In Total
Servo Motors:	12 MX-64 8 MX-28
Sensors:	Accelerometer Gyroscope Compass Logitech C920 Camera
Embedded PC Board:	Fit-PC2i