

**TEAM: ELECATRÓN-LAREDO**  
**INSTITUTO TECNOLÓGICO DE NUEVO LAREDO, MÉXICO.**

ROBOT NAME: TACO

Specification sheet

Measurement chart.

Weight	2.017 kg. – 4.4467 lb.
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Height	42.7 cm. – 16 <sup>13/16</sup> in.
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technical SPEC

Motor type	DYNAMIXEL AX-12 <sup>a</sup>
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Degrees of freedom	20
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Sensor type	GYRO GS-12 HaViMo camera (2.0,3.0)
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CPU	CM- 530
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Walking speed	17 cm./s.
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# ROBOT NAME: TECO

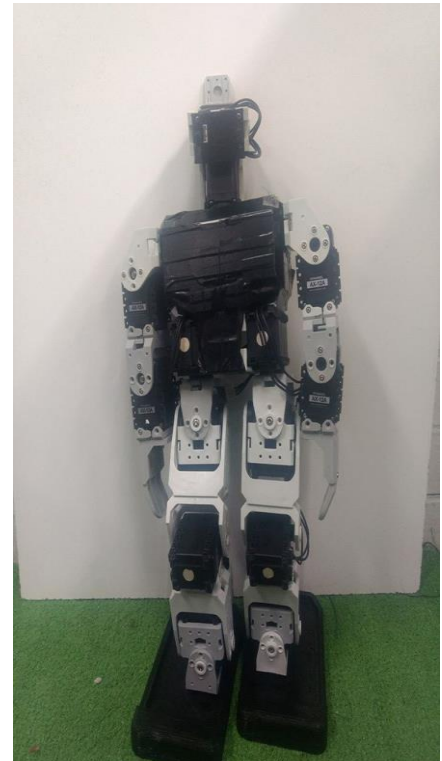
## Specification sheet

### Measurement chart.

Weight	1.865 kg. – 4.1116 lb.
Height	42.7 cm. – 16 <sup>13/16</sup> in.

### technical SPEC

Motor type	DYNAMIXEL AX-12A
Degrees freedom	20
Sensor type	GYRO GS-12 HaViMo camera (2.0,3.0)
CPU	CM- 530
Walking speed	17 cm./s.



# ROBOT NAME: TITO

## Specification sheet

### Measurement chart.

Weight	1.912 kg. – 4.2152 lb.
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Height	42.7 cm. – 16 <sup>13/16</sup> in.
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### Technical SPEC

Motor type	DYNAMIXEL AX-12A
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Degrees of freedom	20
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Sensor type	GYRO GS-12 HaViMo camera (2.0, 3.0)
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CPU	CM- 530
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Walking speed	17 cm./s.
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# ROBOT NAME: TORO

## Specification sheet

### Measurement chart.

Weight	1.806 kg. 3.9815 lb.
Height	42.7 cm. – 16 <sup>13/16</sup> in.

### Technical SPEC

Motor type	DYNAMIXEL AX-12A
Degrees freedom	20
Sensor type	HaViMo camera (2.0,3.0)
CPU	CM-5
Walking speed	17 cm./s.

