

TEAM: ELECATRÓN-LAREDO
INSTITUTO TECNOLÓGICO DE NUEVO LAREDO, MÉXICO.

ROBOT NAME: TACO

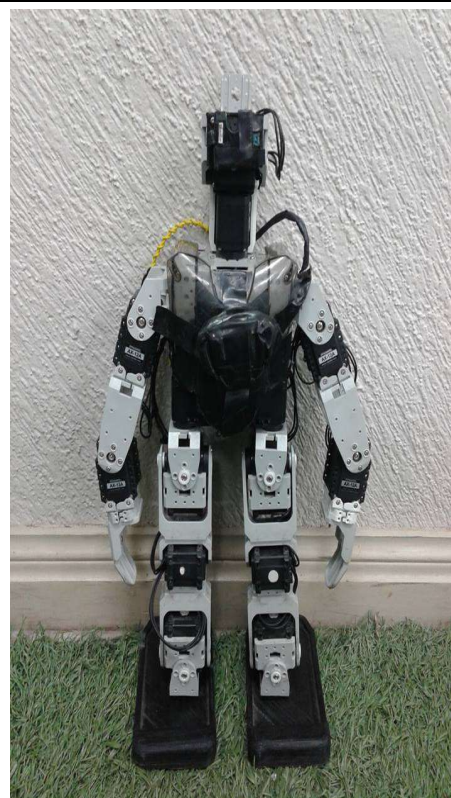
Specification sheet

Measurement chart.

Weight	2.017 kg. – 4.4467 lb.
Height	42.7 cm. – 16 ^{13/16} in.

technical SPEC

Motor type	DYNAMIXEL AX-12 ^a
Degrees of freedom	20
Sensor type	GYRO GS-12 HaViMo camera (2.0,3.0)
CPU	CM- 530
Walking speed	17 cm./s.



ROBOT NAME: TITO

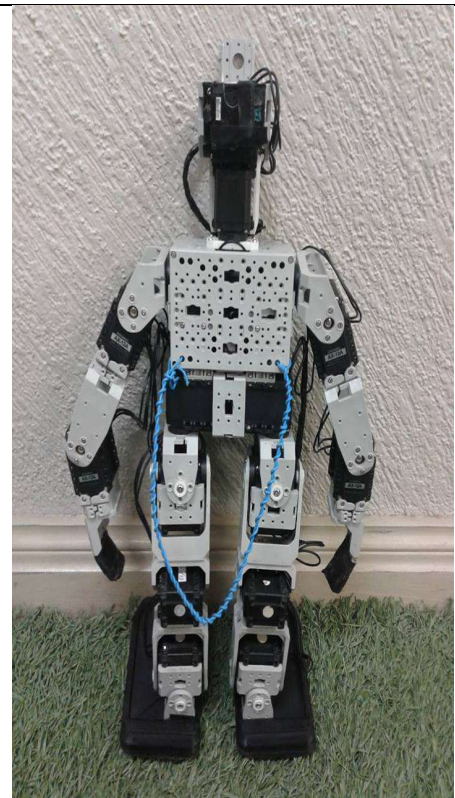
Specification sheet

Measurement chart.

Weight	1.912 kg. – 4.2152 lb.
Height	43 cm. – 16 ^{15/16} in.

Technical SPEC

Motor type	DYNAMIXEL AX-12A
Degrees of freedom	20
Sensor type	GYRO GS-12 HaViMo camera (2.0, 3.0)
CPU	CM- 530
Walking speed	17 cm./s.



ROBOT NAME: TORO

Specification sheet

Measurement chart.

Weight	1.806 kg. 3.9815 lb.
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Height	43.6 cm. – 17 ¹ / ₄ in.
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Technical SPEC

Motor type	DYNAMIXEL AX-12A
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Degrees freedom	20
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Sensor type	HaViMo camera (2.0,3.0)
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CPU	CM-5
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Walking speed	17 cm./s.
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